

① @  $m \frac{dv}{dt} = mg - \gamma v$  with

$m = 10, g = 9.8, \gamma = 2$  becomes

$10 \frac{dv}{dt} = 10(9.8) - 2v$ , or equivalently

$\Rightarrow \frac{dv}{dt} = 9.8 - \frac{1}{5}v = \frac{49-v}{5}$ . This

+1  
plug in

Equation is separable: +1

+3  $\int \frac{dv}{v-49} dt = \int -\frac{1}{5} dt$

+1 for any attempt

$\Rightarrow \ln|v-49| = -\frac{1}{5}t + C$

+1  $\Rightarrow$  So  $v(t) = 49 + Ke^{-t/5}$  is the general solution.

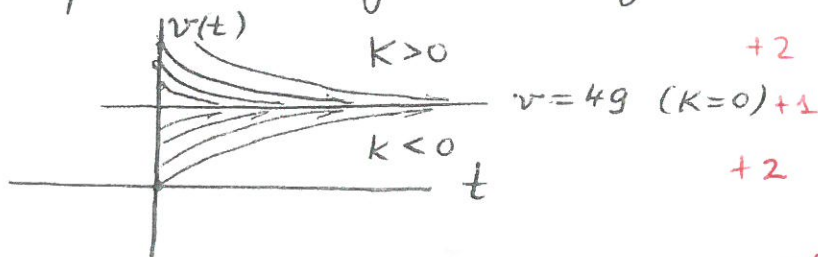
① ⑥ Substituting the IC

+3  $\left\{ \begin{aligned} v(0) = 49 &= 49 + K \cdot e^0 \\ &\Rightarrow K = 0 \end{aligned} \right.$

+2  $\left\{ \begin{aligned} &\text{gives the specific solution } v(t) = 49, \\ &\text{the constant function.} \end{aligned} \right.$

no punishment if  $v(t)$  incorrect but procedure correct

① ⑦  $v(t) = 49 + Ke^{-t/5}$ ; note that  $K$  can be positive, negative or zero



0 pts if totally wrong graph / wrong axes etc.

+1 for partially correct attempt

- ① ④ { points on vertical axis are initial velocities for the falling object  
 (e.g. origin denotes mass is being dropped from rest }  
 +1
- +3 { since  $\lim_{t \rightarrow \infty} (4g + Ke^{-t/5}) = 4g$  for any  $K \in \mathbb{R}$ , we see that irrespective of the initial velocity of the falling object, its velocity will approach  
 (or already equal)  $4g$  m/s (terminal velocity). }  
 +1

Q1 a, b, c coursework  
 d unseen

② a)  $\begin{cases} y' = y \tan x + \sin x & -\frac{\pi}{2} < x < \frac{\pi}{2} \\ y(0) = 1 \end{cases}$

First solve the homogeneous problem

$$y' = y \tan x \Rightarrow \frac{y'}{y} = \tan x$$

$$\ln |y| = \int \tan x \, dx$$

$$\int \tan x \, dx = \int \frac{\sin x}{\cos x} \, dx \stackrel{\substack{\uparrow \\ u = \cos x}}{=} -\ln |\cos x| + C$$

$$\text{So } |y| = e^{-\ln |\cos x| + C} = e^C |\sec x|$$

$$\Rightarrow y = K \sec x$$

Now use variation of parameters for the inhomogeneous problem:  $y(x) = K(x) \sec x$

$$\Rightarrow y'(x) = K'(x) \sec x$$

$$+ K(x) \sec x \tan x$$

$$y' = y \tan x + \sin x \text{ becomes}$$

$$K' \sec x + K \sec x \tan x = K \sec x \tan x + \sin x$$

$$\Rightarrow K'(x) = \sin x \cos x$$

$$\Rightarrow K(x) = \frac{1}{2} \sin^2 x + C$$

$$\text{Soln becomes } y(x) = \left( \frac{1}{2} \sin^2 x + C \right) \sec x$$

$$y(0) = (0 + C) \cdot 1 = 1 \Rightarrow C = 1$$

$$\Rightarrow y(x) = \left( \frac{1}{2} \sin^2 x + 1 \right) \sec x$$

can also use Educated guess for these 4 pts.  
 $y = y_h + y_p$



② ⑥ To apply Picard-Lindelöf Theorem,

10

we need to check the 3 conditions on

$$\mathcal{D} = \{(x, y) : |x-0| \leq A, |y-1| \leq B\} \quad +2$$

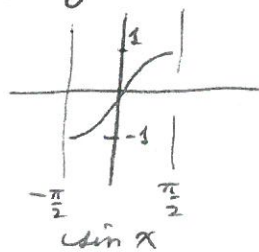
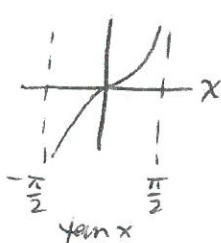
for  $f(x, y) = y \tan x + \sin x$ :

(i)  $f$  is continuous on  $\mathcal{D}$  since  $y$ ,  $\tan x$  and  $\sin x$  are continuous, NOTING that we require  $-\frac{\pi}{2} < x < \frac{\pi}{2}$  so  $A < \frac{\pi}{2}$ . +2

(ii) We need  $A \leq B/M$ , so we must find

$$M = \max_{\mathcal{D}} |f(x, y)| \quad +2$$
$$= \max_{\mathcal{D}} |y \tan x + \sin x| \quad \begin{matrix} \uparrow \\ = (1+B) \tan A + \sin A \end{matrix}$$

• for  $|x| \leq A < \frac{\pi}{2}$ ,  
 $\tan x$  and  $\sin x$   
are increasing functions



max will be at right endpoint of the interval  $[-A, A]$

•  $y$  is an increasing function, so max will be at right endpoint  $-B \leq y-1 \leq B$   
 $\Rightarrow 1-B \leq y \leq 1+B$

(iii)  $\left| \frac{\partial f}{\partial y} \right| = \left| \frac{\partial}{\partial y} (y \tan x + \sin x) \right| = |\tan x|$  is bounded on  $\mathcal{D}$  since  $|x| \leq A < \frac{\pi}{2}$ . +2

② ⑥ (cont'd) Since all 3 hypotheses of the theorem are satisfied, Picard-Lindelöf guarantees a unique solution to the IVP

$$\begin{cases} y'(x) = y \tan x + \sin x \\ y(0) = 1 \end{cases}$$

On the rectangle  $D = \{(x, y) : |x| \leq A < \frac{\pi}{2}, |y-1| \leq B\}$ ,

where  $A, B$  satisfy

$$A \leq \frac{B}{((1+B) \tan A + \sin A)},$$

whatever value obtained for (ii)  
incorrect M not deducted additionally

Q2 a modified from coursework

b unseen, Bookwork

10 ③ a

$$\ln|xy| \frac{dy}{dx} + x^2 + \frac{f(y)}{xy} = 0$$

Q(x,y)

P(x,y)

Equation is Exact if  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$

+3

$$\frac{\partial P}{\partial y} = \frac{f'(y)}{xy} + \frac{f(y)}{x} \left(-\frac{1}{y^2}\right) = \frac{1}{x} \frac{\partial}{\partial y} \left(\frac{f(y)}{y}\right)$$

+2

$$\frac{\partial Q}{\partial x} = \frac{1}{xy} (y) = \frac{1}{x}$$

+2

so  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  becomes  $\frac{1}{x} \frac{\partial}{\partial y} \left(\frac{f(y)}{y}\right) = \frac{1}{x}$

function of y alone

$$\Rightarrow \left(\frac{f(y)}{y}\right)' = 1$$

so  $\frac{f(y)}{y} = y + C$  which means

$$f(y) = y^2 + Cy$$

+3

10 ③ b

If we require  $f(1) = 1$ , then  $C = 0$   
so  $f(y) = y^2$ . To solve  $(1^2 + C \cdot 1 = 1)$

no matter what f from part a

+2

The exact differential Equation, we look for a solution in implicit form  $F(x, y) = C$  which satisfies

③ ⑥ (cont'd)

$$\frac{\partial F^{(1)}}{\partial x} = P(x, y) \quad \text{and} \quad \frac{\partial F^{(2)}}{\partial y} = Q(x, y).$$

$$\begin{aligned} (1) \Rightarrow F(x, y) &= \int P(x, y) dx + g(y) \\ &= \int x^2 + \frac{f(y)}{xy} dx + g(y) \\ &= \frac{1}{3}x^3 + y \ln|x| + g(y) \end{aligned} \quad \left. \vphantom{\int} \right\} +3$$

$$\begin{aligned} \Rightarrow \frac{\partial F}{\partial y} &= \ln|x| + g'(y) \stackrel{(2)}{=} Q(x, y) \\ &= \ln|xy| \\ &= \ln|x| + \ln|y| \end{aligned} \quad \left. \vphantom{\frac{\partial F}{\partial y}} \right\} +3$$

$$\begin{aligned} \Rightarrow g'(y) &= \ln|y| \\ \text{so } g(y) &= y \ln y - y \end{aligned}$$

say  
 $y > 0$   
or use  
abs value  
in  $\ln|y|$

Solution to original ODE is thus

$$\frac{1}{3}x^3 + y \ln|x| + y \ln|y| - y = C. \quad +2$$

Q3 Coursework



④

②

$$x^2 y'' - 2y = 0$$

Let  $x = e^t$  and  $z(t) = y(e^t)$ . Then

$$\dot{z} = y'(e^t) e^t = y'(x) \cdot x \quad (\text{Chain Rule})$$

$$\begin{aligned} \ddot{z} &= y''(e^t) e^{2t} + y'(e^t) e^t \\ &= y''(x) \cdot x^2 + y'(x) \cdot x \end{aligned}$$

$$\Rightarrow x^2 y'' = \ddot{z} - \dot{z} \quad \left\{ \begin{array}{l} \text{where prime denotes} \\ \frac{d}{dx} \text{ and dot denotes} \\ \frac{d}{dt} \text{ on the left.} \end{array} \right.$$

Thus

$$x^2 y'' - 2y = \ddot{z} - \dot{z} - 2z = 0.$$

Solving  $\ddot{z} - \dot{z} - 2z = 0$  using  $z(t) = e^{\lambda t}$  gives characteristic equation

$$\lambda^2 - \lambda - 2 = 0$$

$$(\lambda - 2)(\lambda + 1) = 0 \Rightarrow \lambda = -1, 2$$

So the general solution to the  $z$ -equation

is  $z(t) = C_1 e^{-t} + C_2 e^{2t}$  which

then gives the general solution to the original equation as  $x = e^t$

$$y(x) = \frac{C_1}{x} + C_2 x^2.$$



④⑤ Let  $\mathcal{L}(y) = x^2 y'' - 2y$ . The left-end and right-end IVPs are given by examining the BCs:

$$y(1) = 0, \quad y(2) + 2y'(2) = 0$$

$$\Rightarrow [x_1, x_2] = [1, 2], \quad \alpha = 0, \quad \gamma = 2 \\ \beta = 1, \quad \delta = 1$$

Left-End IVP

$$+2 \begin{cases} \mathcal{L}(y) = 0 \\ y(1) = 0 \\ y'(1) = -1 \end{cases}$$

Right-End IVP

$$\begin{cases} \mathcal{L}(y) = 0 \\ y(2) = 2 \\ y'(2) = -1 \end{cases} +2$$

Note: From part (a) we have  $\mathcal{L}(y) = 0$  is solved by  $y(x) = \frac{C_1}{x} + C_2 x^2$ , so we find  $C_1, C_2$  in each IVP, noting  $y'(x) = -\frac{C_1}{x^2} + 2C_2 x$

$$\begin{cases} y(1) = C_1 + C_2 = 0 \\ y'(1) = -C_1 + 2C_2 = -1 \end{cases}$$

$$\Rightarrow \begin{cases} C_1 = \frac{1}{3} \\ C_2 = -\frac{1}{3} \end{cases}$$

$$y_L(x) = \frac{1}{3x} - \frac{1}{3}x^2$$

$$\begin{cases} y(2) = \frac{C_1}{2} + 4C_2 = 2 \\ y'(2) = -\frac{C_1}{4} + 4C_2 = -1 \end{cases}$$

$$\Rightarrow \begin{cases} C_1 = 4 \\ C_2 = 0 \end{cases}$$

$$y_R(x) = \frac{4}{x}$$

④ ③  $G(x, s) = \begin{cases} A(s)y_L(x) & 1 \leq x \leq s \\ B(s)y_R(x) & s \leq x \leq 2 \end{cases}$

5

where  $A(s)$  &  $B(s)$  are defined as

$$A(s) = \frac{y_R(s)}{a_2(s)W(s)}, \quad B(s) = \frac{y_L(s)}{a_2(s)W(s)}$$

Here,  $a_2(s) = s^2$  and

+1  $W(s) = y_L(s)y_R'(s) - y_R(s)y_L'(s)$

$$= \left(\frac{1}{3x} - \frac{1}{3}x^2\right)\left(-\frac{4}{x^2}\right) - \frac{4}{x}\left(-\frac{1}{3x^2} - \frac{2}{3}x\right)$$

$$= \frac{-4}{3x^3} + \frac{4}{3} + \frac{4}{3x^3} + \frac{8}{3}$$

$$= 4$$

thus

+1  $A(s) = \frac{4/s}{s^2 \cdot 4} = \frac{1}{s^3}$

+1  $B(s) = \frac{1/3s - \frac{1}{3}s^2}{s^2 \cdot 4} = \frac{1}{12s^3} - \frac{1}{12}$

+2  $\Rightarrow G(x, s) = \begin{cases} \frac{1}{s^3} \left(\frac{1}{3x} - \frac{x^2}{3}\right) & 1 \leq x \leq s \\ \frac{1}{3} \left(\frac{1}{s^3} - 1\right) \frac{1}{x} & s \leq x \leq 2 \end{cases}$

④ ②  $y(x) = \int_1^2 G(x, s) e^s ds$

④ ⑤

5

$$y(x) = \int_1^2 G(x,s) e^s ds + 1$$

$$= \int_1^x \frac{1}{3} \left( \frac{1}{x^3} - x \right) \frac{1}{s} e^s ds + 2$$

$$+ \int_x^2 \frac{1}{x^3} \left( \frac{1}{3s} - \frac{s^2}{3} \right) e^s ds + 2$$

Q4 a, b, c, d Bookwork / Modified  
from Coursework

⑤ a  $\begin{cases} \dot{x} = 4y \\ \dot{y} = -x \end{cases}$  has fixed points where

part ①  $\left\{ \begin{aligned} \begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ i.e. } \begin{cases} 4y = 0 \\ -x = 0 \end{cases} \text{ so there is} \\ \text{one fixed point } (x(t), y(t)) = (0, 0). \end{aligned} \right.$

⑤ b  $\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} 0 & 4 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

5  $A = \begin{pmatrix} 0 & 4 \\ -1 & 0 \end{pmatrix}$  has eigenvalues  $\lambda$  given

by  $\det(A - \lambda I) = 0$

$$\det \begin{pmatrix} -\lambda & 4 \\ -1 & -\lambda \end{pmatrix} = 0$$

$$\lambda^2 + 4 = 0$$

$$\lambda = \pm 2i \quad +2$$

Associated eigenvectors will be complex conjugates so we find one of them

$\lambda = 2i$  has eigenvector satisfying

$$Av = \lambda v = 2i v \Leftrightarrow \begin{pmatrix} 0 & 4 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} = 2i \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

$$\begin{cases} 4v_2 = 2i v_1 \\ -v_1 = 2i v_2 \end{cases}$$

choose  $v_2 = 1 \Rightarrow v_1 = -2i$

$$\Rightarrow v_{\lambda \pm} = \begin{pmatrix} \mp 2i \\ 1 \end{pmatrix} \quad +2$$



⑤ ⑥ The general solution to the system is given by

5

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = c_1 e^{\lambda_1 t} v_{\lambda_1} + c_2 e^{\lambda_2 t} v_{\lambda_2}$$

+2 } 
$$= c_1 e^{2it} \begin{pmatrix} -2i \\ 1 \end{pmatrix} + c_2 e^{-2it} \begin{pmatrix} 2i \\ 1 \end{pmatrix}$$

Imposing the initial conditions

$$\begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} x(0) \\ y(0) \end{pmatrix} = c_1 \begin{pmatrix} -2i \\ 1 \end{pmatrix} + c_2 \begin{pmatrix} 2i \\ 1 \end{pmatrix}$$

+1 
$$\Rightarrow \begin{cases} a = 2i(c_2 - c_1) \\ b = c_1 + c_2 \end{cases}$$

+2 
$$\Rightarrow \begin{cases} c_1 = \frac{1}{2} \left( b - \frac{a}{2i} \right) \\ c_2 = \frac{1}{2} \left( b + \frac{a}{2i} \right) \end{cases}$$

⑤ ⑥ To sketch the phase portrait, we need

the real solution:

$$x(t) = 2i(-c_1 e^{2it} + c_2 e^{-2it})$$

$$= 2i(-c_1 [\cos 2t + i \sin 2t] + c_2 [\cos 2t - i \sin 2t])$$

+1 
$$= 2i([c_2 - c_1] \cos 2t - i[c_1 + c_2] \sin 2t)$$

$$= 2i\left(\frac{a}{2i} \cos 2t - i b \sin 2t\right)$$

$$= a \cos 2t + 2b \sin 2t$$

+2 for any attempt in this direction

5 (c) (Continued)

$$y(t) = c_1 e^{2it} + c_2 e^{-2it}$$

$$= c_1 [\cos 2t + i \sin 2t] + c_2 [\cos 2t - i \sin 2t]$$

$$+1 = [c_1 + c_2] \cos 2t + i [c_1 - c_2] \sin 2t$$

$$= b \cos 2t + i \left( \frac{-a}{2i} \right) \sin 2t$$

$$= b \cos 2t - \frac{a}{2} \sin 2t$$

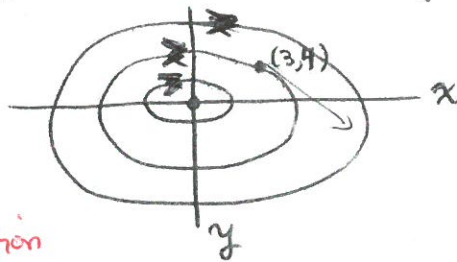
Notice that

$$x^2 = a^2 \cos^2 2t + 4ab \cos 2t \sin 2t + 4b^2 \sin^2 2t$$

$$y^2 = b^2 \cos^2 2t - ab \cos 2t \sin 2t + \frac{a^2}{4} \sin^2 2t$$

$$\Rightarrow x^2 + 4y^2 = a^2 + 4b^2$$

which are ellipses



+1  
The IC (3,4) has a unique ellipse passing through that point which satisfies the dynamical system.

+1  
no credit for wrong diagram with no explanation

5 (d) The zero solution is a centre and it

5 is a stable equilibrium } with

$$\lim_{t \rightarrow \infty} x(t) = 0$$

+2 One fixed point:  $\begin{pmatrix} \dot{x} \\ \dot{y} \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$  when  $\begin{cases} 4y = 0 \\ -x^2 = 0 \end{cases}$

5 a, b, c, d Coursework / Modified Coursework

why? either from correct phase diagram or explained from eigenvalues

+1 if incorrect but justified via eigenvalues